# Table of contents

1. **Introduction** .................................................................................................................................................. 3
   1.1 Purpose and use of this manual .................................................................................................................. 3
   1.2 Used symbols and warnings ....................................................................................................................... 3

2. **Safety instructions** ......................................................................................................................................... 3
   2.1 Intended use .................................................................................................................................................. 3
   2.2 Foreseeable misuse ..................................................................................................................................... 3
   2.3 Installation, commissioning and operation ................................................................................................. 4
   2.4 Safety instructions for use in explosion-hazardous areas ........................................................................... 5
   2.5 Warranty ..................................................................................................................................................... 5
   2.6 Return .......................................................................................................................................................... 5

3. **Identification** .................................................................................................................................................. 6
   3.1 Order code Temposonics® ET ..................................................................................................................... 6
   3.2 Nameplate (example) .................................................................................................................................. 7
   3.3 Approvals ................................................................................................................................................... 7
   3.4 Scope of delivery ......................................................................................................................................... 7

4. **Product description and commissioning** ...................................................................................................... 7
   4.1 Functionality and system design .................................................................................................................. 7
   4.2 Installation and design of Temposonics® ET (rod style) ............................................................................. 8
   4.3 Magnet installation ....................................................................................................................................... 10
   4.4 Electrical connection .................................................................................................................................... 11
   4.5 Frequently ordered accessories for ET-F/-W/-M/-S ................................................................................. 12
   4.6 Frequently ordered accessories for Start/Stop output ............................................................................... 13

5. **Operation** .................................................................................................................................................... 14
   5.1 Getting started ............................................................................................................................................ 14
   5.2 Programming and configuration .................................................................................................................. 14

6. **Maintenance and troubleshooting** ............................................................................................................... 16
   6.1 Error conditions, troubleshooting ............................................................................................................. 16
   6.2 Maintenance ............................................................................................................................................... 16
   6.3 Repair ......................................................................................................................................................... 16
   6.4 List of spare parts ....................................................................................................................................... 16
   6.5 Transport and storage ................................................................................................................................. 16

7. **Removal from service/dismantling** .............................................................................................................. 16
8. **Technical data of Temposonics® ET** ............................................................................................................ 17
9. **Appendix** .................................................................................................................................................... 19
10. **Declaration of conformity** .......................................................................................................................... 20
1. Introduction

1.1 Purpose and use of this manual

Before starting the operation of Temposonics position sensors, read this documentation thoroughly and follow the safety information. Keep this manual for future reference!

The content of this technical documentation and of its appendix is intended to provide information on mounting, installation and commissioning by qualified automation personnel or instructed service technicians who are familiar with the project planning and dealing with Temposonics sensors.

1.2 Used symbols and warnings

Warnings are intended for your personal safety and for avoidance of damage to the described product or connected devices. In this documentation, safety information and warnings to avoid danger that might affect the life and health of operating as well as service personnel or cause material damage are highlighted by the preceding pictogram, which is defined below.

Symbol | Meaning
--- | ---
NOTICE | This symbol is used to point to situations that may lead to material damage, but not to personal injury.

2. Safety instructions

2.1 Intended use

This product may be used only for the applications defined under item 1 to item 4 and only in conjunction with the third-party devices and components recommended or approved by Temposonics. As a prerequisite of proper and safe operation, the product requires correct transport, storage, mounting and commissioning and must be operated with utmost care.

1. The sensor systems of all Temposonics® series are intended exclusively for measurement tasks encountered in industrial, commercial and laboratory applications. The sensors are considered as system accessories and must be connected to suitable evaluation electronics, e.g. a PLC, IPC, indicator or other electronic control unit.

2. The sensor’s surface temperature class is T4.

3. The ATEX, UK Ex, IECEx, CEC, NEC and CCC certificates have to be taken into account, including any special conditions defined therein, as well as chapter “2.3 Installation, commissioning and operation” on page 4.

4. The position sensor may be used in hazardous areas according to Fig. 23. Any use of this product outside of these approved areas will void the warranty and all manufacturer’s product responsibilities and liabilities. For non-hazardous areas Temposonics recommends to use the version N (not approved).

<table>
<thead>
<tr>
<th>Zone</th>
<th>Explosion group</th>
</tr>
</thead>
<tbody>
<tr>
<td>Zone 2 (Gas-Ex, category 3G, EPL Gc)</td>
<td>IIA, IIB and IIC</td>
</tr>
<tr>
<td>Zone 22 (Dust-Ex, category 3D, EPL Dc)</td>
<td>IIIA, IIIB and IIIC</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Class</th>
<th>Group</th>
</tr>
</thead>
<tbody>
<tr>
<td>Class I (Gas, Division 2)</td>
<td>A, B, C, D</td>
</tr>
<tr>
<td>Class II/III (Dust, Division 2)</td>
<td>F, G</td>
</tr>
</tbody>
</table>

2.2 Forseeable misuse

<table>
<thead>
<tr>
<th>Forseeable misuse</th>
<th>Consequence</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lead compensating currents through the enclosure</td>
<td>The sensor will be damaged</td>
</tr>
<tr>
<td>Wrong sensor connection</td>
<td>The sensor will not work properly or will be destroyed</td>
</tr>
<tr>
<td>Operate the sensor out of the operating temperature range</td>
<td>No signal output</td>
</tr>
<tr>
<td>Power supply is out of the defined range</td>
<td>Signal output is wrong / no signal output / the sensor will be damaged</td>
</tr>
<tr>
<td>Position measurement is influenced by an external magnetic field</td>
<td>Signal output is wrong</td>
</tr>
<tr>
<td>Cables are damaged</td>
<td>Short circuit – the sensor can be destroyed / sensor does not respond</td>
</tr>
<tr>
<td>Spacers are missing / are installed in a wrong order</td>
<td>Error in position measurement</td>
</tr>
<tr>
<td>Wrong connection of ground/shield</td>
<td>Signal output is disturbed</td>
</tr>
<tr>
<td>Use of a magnet that is not certified by Temposonics</td>
<td>The electronics can be damaged</td>
</tr>
<tr>
<td>Wrong gradient in controller</td>
<td>Error in position measurement</td>
</tr>
</tbody>
</table>

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1/ The term qualified technical personnel characterizes persons who:
- are familiar with the safety concepts of automation technology applicable to the particular project
- are competent in the field of electromagnetic compatibility (EMC)

• have received adequate training for commissioning and service operations
• are familiar with the operation of the device and know the information required for correct operation provided in the product documentation
The position sensors must be used only in technically safe condition. To maintain this condition and to ensure safe operation, installation, connection and service, work may be performed only by qualified technical personnel, according to IEC 60079-14, IEC 60079-17, TRBS 1203, Canadian Electrical Code (CEC), National Electrical Code (NEC), China Compulsory Certification (CCC) and local regulations.

If danger of injury to persons or of damage to operating equipment is caused by sensor failure or malfunction, additional safety measures such as plausibility checks, limit switches, EMERGENCY STOP systems, protective devices etc. are required. In the event of trouble, shut down the sensor and protect it against accidental operation.

Safety instructions for commissioning
To maintain the sensor’s operability, it is mandatory to follow the instructions given below.
1. Follow the specifications given in the technical data.
2. Ensure that equipment and associated components used in a hazardous environment are selected and installed in compliance with regulations governing the geographical location and facility. Only install equipment that complies with the types of protection relevant to the applicable Zones and Categories.
3. In explosive atmospheres use only such auxiliary components that meet all requirements of the local and national standards.
4. The potential equalisation of the system has to be established according to the regulations of erection applicable in the respective country of use (VDE 0100, part 540; IEC 364-5-54).
5. Sensors from Temposonics are approved only for the intended use in industrial environments (see chapter “2.1 Intended use” on page 3). Contact the manufacturer for advice, if aggressive substances are present in the sensor environment.
6. Measures for lightning protection have to be taken by the user.
7. The user is responsible for the mechanical protection of the sensor.
8. The cable gland of the sensor must be protected against any external impact energy exceeding 4 J. The maximum thermal load of the cables must be taken into account.
9. The user is responsible for meeting all safety conditions as outlined by:
   • Installation instructions
   • Local prevailing standards and regulations
10. Any parts of the equipment which got stuck (e.g. by frost or corrosion) may not be removed by force if potentially explosive atmosphere is present.
11. The formation of ice on the equipment has to be prevented.
12. It is not allowed to open the sensor.
13. The connecting cable has to be either led out of the hazardous area uncut or wired to outlets which comply with the type of protection required locally.
14. The surface temperatures of equipment parts must be kept clearly below the ignition temperature of the foreseeable air/dust mixtures in order to prevent the ignition of suspended dust.

How to ensure safe commissioning
1. Protect the sensor against mechanical damage during installation and operation.
2. Do not use damaged products and secure them against unintentional commissioning. Mark damaged products as being defective.
3. Prevent electrostatic charges.
4. Do not use the sensor in cathodic systems for corrosion protection. Do not lead parasitic currents via the construction.
5. Switch off the supply voltage prior to disconnecting or connecting the equipment.
6. Connect the sensor very carefully and pay attention to the polarity of connections, power supply as well as where appropriate to the shape and duration of control pulses.
7. Use only approved power supplies.
8. Ensure that the specified permissible limit values of the sensor for supply voltage, environmental conditions, etc. are met.
9. Make sure that:
   • the sensor and associated components were installed according to the instructions
   • the sensor enclosure is clean
   • the magnet does not grind on the rod. This could cause damage to the magnet and the sensor rod. If there is contact between the moving magnet including the magnet holder and the sensor rod, make sure that the maximal speed of the moving magnet is less or equal 1 m/s.
10. Ground the sensor via the ground lug. Both the sensor and the moving magnet including magnet holder must be connected to protective ground (PE) to avoid electrostatic discharge (ESD).
11. Before applying power, ensure that nobody’s safety is jeopardized by starting machines.
12. Check the function of the sensor regularly and provide documentation of the checks.
   (see chapter “6.2 Maintenance” on page 16).
2.4 Safety instructions for use in explosion-hazardous areas

The sensor has been designed for operation inside explosion-hazarded areas. It has been tested and left the factory in a condition in which it is safe to operate. Relevant regulations and European standards as well as Canadian and North American standards have been observed. According to Ex marking (see chapter “2.1 Intended use” on page 3) and the ATEX und UK Ex certificates (attached to this document), the sensor is approved only for operation in defined hazardous areas. All other certificates can be found at: www.temposonics.com.

2.5 Warranty

Temposonics grants a warranty period for the position sensors and supplied accessories relating to material defects and faults that occur despite correct use in accordance with the intended application. The Temposonics obligation is limited to repair or replacement of any defective part of the unit. No warranty can be provided for defects that are due to improper use or above average stress of the product, as well as for wear parts. Under no circumstances will Temposonics accept liability in the event of offense against the warranty rules, no matter if these have been assured or expected, even in case of fault or negligence of the company. Temposonics explicitly excludes any further warranties. Neither the company’s representatives, agents, dealers nor employees are authorized to increase or change the scope of warranty.

2.6 Return

For diagnostic purposes, the sensor can be returned to Temposonics. Any shipment cost is the responsibility of the sender. For a corresponding form, see chapter “9. Appendix” on page 19.

NOTICE

When returning sensors, place protective caps on male and female connectors of the sensor. For pigtail cables, place the cable ends in a static shielding bag for electrostatic discharge (ESD) protection. Fill the outer packaging around the sensor completely to prevent damage during transport.
3. Identification

### 3.1 Order code Temposonics® ET

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<td>b</td>
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<td>100…118 in.</td>
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<td></td>
<td>T01…T10 (1…10 m) XX m FEP cable (part no. 530 112)</td>
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<td>T03…T33 (3…33 ft.) XX ft. FEP cable (part no. 530 112)</td>
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<td>V01…V10 (1…10 m) XX m silicone cable (part no. 530 113)</td>
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<td>e</td>
<td>Operating voltage</td>
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<td>f</td>
<td>Version (see “Certification of Temposonics® ET (version A and E)” on page 26 for further information)</td>
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<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>N Not approved</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>g</td>
<td>Output</td>
<td>R 3 Start/Stop with sensor parameters upload function</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**NOTICE**

Version E (section  R  ) is only available with design »M« and »S« (section  S  ).

Non-standard stroke lengths are available; must be encoded in 5 mm/0.1 in. increments.
3.2 Nameplate (example)

See chapter “8. Technical data of Temposonics® ET” on page 17 f.

3.4 Scope of delivery

ET (rod sensor):
• Sensor

4. Product description and commissioning

4.1 Functionality and system design

Product designation
• Position sensor Temposonics® E-Series

Sensor model
• Temposonics® E-Series ET (rod sensor)

Stroke length
• 50…3000 mm (2…118 in.)

Output signal
• Start/Stop

Application
Temposonics position sensors are used for measurement and conversion of the length (position) variable in the fields of automated systems and mechanical engineering.

Principle of operation and system construction
The absolute, linear position sensors provided by Temposonics rely on the company’s proprietary Temposonics® magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the end of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

Modular mechanical and electronic construction
• The sensor rod protects the inner sensor element.
• The sensor electronics housing, a rugged stainless steel construction, contains the complete electronic interface with active signal conditioning.
• The external position magnet is a permanent magnet. Mounted on the mobile machine part, it travels along the sensor rod and triggers the measurement through the sensor rod wall.
• The sensor can be connected directly to a control system. Its electronics generates a strictly position proportional signal output between start and end position.
## 4.2 Installation and design of Temposonics® ET

### ET-F/-M/-S/-W, example: Version A/N

<table>
<thead>
<tr>
<th>Sensor electronics housing</th>
<th>Null zone</th>
<th>Stroke length</th>
<th>Dead zone</th>
</tr>
</thead>
<tbody>
<tr>
<td>~34</td>
<td>50</td>
<td>50...3000</td>
<td>63.5</td>
</tr>
<tr>
<td>(1.34)</td>
<td>(1.97)</td>
<td>(2...118)</td>
<td>(2.5)</td>
</tr>
</tbody>
</table>

- FEP cable: Ø 7.6 (Ø 0.3) 
- Silicone cable: Ø 7.2 (Ø 0.28)

**Threaded flange**
- »M« / »W«: M18×1.5-6g
- »F« / »S«: ¾"-16 UNF-3A

### ET-F/-M/-S/-W, example: Version E

<table>
<thead>
<tr>
<th>Sensor electronics housing</th>
<th>Null zone</th>
<th>Stroke length</th>
<th>Dead zone</th>
</tr>
</thead>
<tbody>
<tr>
<td>~60</td>
<td>50</td>
<td>50...3000</td>
<td>63.5</td>
</tr>
<tr>
<td>(2.36)</td>
<td>(1.97)</td>
<td>(2...118)</td>
<td>(2.5)</td>
</tr>
</tbody>
</table>

- FEP cable: Ø 7.6 (Ø 0.3) 
- Silicone cable: Ø 7.2 (Ø 0.28)

**Threaded flange**
- »M« / »W«: M18×1.5-6g
- »F« / »S«: ¾"-16 UNF-3A

Controlling design dimensions are in millimeters and measurements in ( ) are in inches

**Installation of ET with threaded flange »F«, »M«, »S« & »W«**

Fix the sensor rod via threaded flange M18×1.5-6g or ¾"-16 UNF-3A. Lightly oil the thread before tightening. Lightly oil the thread before tightening.

![Installation of a rod-style sensor in a fluid cylinder](image)

**Installation of a rod-style sensor in a fluid cylinder**

The rod-style version has been developed for direct stroke measurement in a fluid cylinder. Mount the sensor via threaded flange or a hex nut.

- Mounted on the face of the piston, the position magnet travels over the rod without touching it and indicates the exact position through the rod wall – independent of the hydraulic fluid.
- The pressure resistant sensor rod is installed into a bore in the piston rod.

![Position magnet](image)
Hydraulics sealing

There are two ways to seal the flange contact surface (Fig. 7):

1. A sealing by using an O-ring (e.g. 22.4 × 2.65 mm (0.88 × 0.1 in.), 25.07 × 2.62 mm (0.99 × 0.1 in.)) in a cylinder end cap groove.

2. A sealing by using an O-ring in the undercut.

   For threaded flange (¾”-16 UNF-3A) »F«/»S«:
   O-ring 16.4 × 2.2 mm (0.65 × 0.09 in.) (part no. 560 315)

   For threaded flange (M18×1.5-6g) »M«/»W«:
   O-ring 15.3 × 2.2 mm (0.60 × 0.09 in.) (part no. 401 133)

![Sealing via O-ring in cylinder end cap groove](image1)

![Sealing via O-ring in the flange undercut](image2)

Fig. 7: Possibilities of sealing

- Note the fastening torque of 75 Nm.
- Seat the flange contact surface completely on the cylinder mounting surface.
- The cylinder manufacturer determines the pressure-resistant gasket (copper gasket, O-ring, etc.).
- The position magnet should not grind on the sensor rod.
- The piston rod drilling (≥ Ø 13 mm (≥ Ø 0.51 in.)) depends on the pressure and piston speed.
- Adhere to the information relating to operating pressure.
- Protect the sensor rod against wear.

In the case of threaded flange M18×1.5-6g provide a screw hole based on ISO 6149-1 (Fig. 8). See ISO 6149-1 for further information.

### Notice for metric threaded flange

<table>
<thead>
<tr>
<th>Thread (d × P)</th>
<th>d₂</th>
<th>d₃</th>
<th>d₄</th>
<th>d₅</th>
<th>L₁</th>
<th>L₂</th>
<th>L₃</th>
<th>L₄</th>
<th>Z°</th>
</tr>
</thead>
<tbody>
<tr>
<td>ET-F/-M/-S/-W</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>±1°</td>
</tr>
<tr>
<td>M18×1.5-6g</td>
<td>55</td>
<td>≥ 13</td>
<td>24.5</td>
<td>19.8</td>
<td>2.4</td>
<td>28</td>
<td>2</td>
<td>≥ 25.5</td>
<td>15°</td>
</tr>
</tbody>
</table>

![Controlling design dimensions](image3)

Fig. 8: Notice for metric threaded flange M18×1.5-6g based on DIN ISO 6149-1
4.3 Magnet installation

### Typical use of magnets

<table>
<thead>
<tr>
<th>Magnet</th>
<th>Typical sensors</th>
<th>Benefits</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ring magnets</td>
<td>Rod model</td>
<td>• Rotationally symmetrical magnetic field</td>
</tr>
<tr>
<td></td>
<td>(ET-F/-W/-M/-S)</td>
<td></td>
</tr>
<tr>
<td>U-magnets</td>
<td>Profile &amp; rod models</td>
<td>• Height tolerances can be compensated, because the magnet can be lifted off</td>
</tr>
<tr>
<td></td>
<td>(ET-P/-F/-W/-M/-S)</td>
<td></td>
</tr>
<tr>
<td>Block magnets</td>
<td>Profile &amp; rod models</td>
<td>• Height tolerances can be compensated, because the magnet can be lifted off</td>
</tr>
<tr>
<td></td>
<td>(ET-P/-F/-W/-M/-S)</td>
<td></td>
</tr>
</tbody>
</table>

![Fig. 9: Typical use of magnets](image)

**Mounting ring magnets, U-magnets & block magnets**

Install the magnet using non-magnetic material for mounting device, screws, spacers etc. The magnet must not grind on the sensor rod. Alignment errors are compensated via the air gap.

- Permissible surface pressure: Max. 40 N/mm² (only for ring magnets and U-magnets)
- Fastening torque for M4 screws: 1 Nm; use washers, if necessary
- Minimum distance between position magnet and any magnetic material has to be 15 mm (0.6 in.) (Fig. 11).
- If no other option exists and magnetic material is used, observe the specified dimensions (Fig. 11).

**NOTICE**

- Mount ring magnets and U-magnets concentrically.
- Mount block magnets centrically over the sensor rod or the sensor profile. The maximum permissible air gap must not be exceeded (Fig. 13/Fig. 14). Take care to mount the primary sensor axis in parallel to the magnet path in order to avoid damage to the carriage, magnet and sensor rod profile.

![Fig. 10: Mounting of U-magnet (part no. 251 416-2)](image)

**Magnet mounting with magnetic material**

When using magnetic material the dimensions of Fig. 11 must be observed.

A. If the position magnet aligns with the drilled piston rod
B. If the position magnet is set further into the drilled piston rod, install another non-magnetic spacer (e.g. part no. 400 633) above the magnet.

![Fig. 11: Installation with magnetic material](image)

**Sensors with stroke lengths ≥ 1 meter (3.3 ft.)**

Support horizontally installed sensors with a stroke length of 1 meter (3.3 ft.) and more mechanically at the rod end. Without using a support, the sensor rod bends over and the rod and the position magnet may be damaged. A false measurement result is also possible. Longer rods require evenly distributed mechanical support over the entire length (e.g. part no. 561 481). Use an U-magnet (Fig. 12) for measurement.

![Fig. 12: Example of sensor support (part no. 561 481)](image)

Controlling design dimensions are in millimeters and measurements in ( ) are in inches.
Start and end positions of the position magnets
Consider the start and end positions of the position magnets during the installation. To ensure that the entire stroke length is electrically usable, the position magnet must be mechanically mounted as follows.

![Fig. 13: Start and end positions of magnets](image)

**NOTICE**

On all sensors, the areas left and right of the active stroke length are provided for null and dead zone (see “4.2 Styles and installation of Temposonics® ET” on page 8). These zones should not be used for measurement, however the active stroke length can be exceeded.

### 4.4 Electrical connection

Placement of installation and cabling have decisive influence on the sensor’s electromagnetic compatibility (EMC). Hence correct installation of this active electronic system and the EMC of the entire system must be ensured by using suitable metal connectors, shielded cables and grounding. Overvoltages or faulty connections can damage the sensor electronics despite protection against wrong polarity.

**NOTICE**

1. Do not mount the sensors in the area of strong magnetic or electric noise fields.
2. Never connect/disconnect the sensor when voltage is applied.

**Instruction for connection**

- Connect the shield to ground externally via the controller equipment.
- Keep control and signal leads separate from power cables and sufficiently far away from motor cables, frequency inverters, valve lines, relays, etc.
- Use only connectors with metal housing, if you use a connector. Connect the shielding to the connector housing.
- Keep all non-shielded leads as short as possible.
- Keep the earth connection as short as possible with a large cross section. Avoid ground loops.

Controlling design dimensions are in millimeters and measurements in ( ) are in inches

### Connector wiring

Connect the sensor directly to the controller, indicator or other evaluating systems as follows:

<table>
<thead>
<tr>
<th>Cable</th>
<th>Color</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>GY</td>
<td>Stop</td>
<td>(−)</td>
</tr>
<tr>
<td>PK</td>
<td>Stop</td>
<td>(+)</td>
</tr>
<tr>
<td>YE</td>
<td>Start</td>
<td>(+)</td>
</tr>
<tr>
<td>GN</td>
<td>Start</td>
<td>(−)</td>
</tr>
<tr>
<td>BN</td>
<td>+24 VDC</td>
<td>(−15/+20 %)</td>
</tr>
<tr>
<td>WH</td>
<td>DC Ground</td>
<td>(0 V)</td>
</tr>
</tbody>
</table>

![Fig. 16: Connector wiring TXX/VXX](image)

**Grounding of rod sensors**

Connect the sensor electronics housing to machine ground. Ground sensor type ET version A (with ATEX/IECEx/CEC NEC/CCC approval) via ground lug as shown in Fig. 14. Ground the sensor type ET version N (not approved) via ground lug as shown in Fig. 14 or via thread. Ground sensor type ET version E (with ATEX/IECEx/CEC NEC/CCC approval) via ground lug as shown in Fig. 15.

![Fig. 14: Grounding via ground lug (version A, N)](image)

![Fig. 15: Grounding via ground lug (version E)](image)
### 4.5 Frequently ordered accessories for ET-F/-W/-M/-S – Additional options available in our Accessories Catalog [551.444]

#### Position magnets

<table>
<thead>
<tr>
<th>U-magnet OD33</th>
<th>Ring magnet OD33</th>
<th>Ring magnet OD25.4</th>
<th>Ring magnet OD17.4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Part no. 251 416-2</td>
<td>Part no. 201 542-2</td>
<td>Part no. 400 533</td>
<td>Part no. 401 032</td>
</tr>
<tr>
<td>Weight: Approx. 11 g</td>
<td>Weight: Approx. 14 g</td>
<td>Weight: Approx. 10 g</td>
<td>Weight: Approx. 5 g</td>
</tr>
<tr>
<td>Surface pressure: Max. 40 N/mm²</td>
<td>Surface pressure: Max. 40 N/mm²</td>
<td>Surface pressure: Max. 40 N/mm²</td>
<td>Surface pressure: Max. 20 N/mm²</td>
</tr>
<tr>
<td>Fastening torque for M4 screws: 1 Nm</td>
<td>Fastening torque for M4 screws: 1 Nm</td>
<td>Fastening torque for M4 screws: 1 Nm</td>
<td>Operating temperature: -40…+105 °C (-40…+221 °F)</td>
</tr>
<tr>
<td>Operating temperature: -40…+105 °C (-40…+221 °F)</td>
<td></td>
<td>Operating temperature: -40…+105 °C (-40…+221 °F)</td>
<td></td>
</tr>
</tbody>
</table>

#### Position magnets

<table>
<thead>
<tr>
<th>U-magnet OD63.5</th>
<th>Block magnet L</th>
<th>Magnet spacer</th>
<th>O-ring for threaded flange</th>
</tr>
</thead>
<tbody>
<tr>
<td>Part no. 201 553</td>
<td>Part no. 403 448</td>
<td>Part no. 400 633</td>
<td>M18×1.5-6g Part no. 401 133</td>
</tr>
<tr>
<td>Weight: Approx. 26 g</td>
<td>Weight: Approx. 20 g</td>
<td>Durometer: 75 ± 5 Shore A</td>
<td>Durometer: 75 ± 5 Shore A</td>
</tr>
<tr>
<td>Surface pressure: 20 N/mm²</td>
<td>Fastening torque for M4 screws: 1 Nm</td>
<td>Operating temperature: -40…+204 °C (-40…+400 °F)</td>
<td></td>
</tr>
<tr>
<td>Operating temperature: -40…+75 °C (-40…+167 °F)</td>
<td>Operating temperature: -40…+75 °C (-40…+167 °F)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

#### O-ring

<table>
<thead>
<tr>
<th>O-ring for threaded flange</th>
<th>Hex jam nut M18×1.5-6g</th>
<th>Hex jam nut ½&quot;-16 UNF-3A</th>
<th>Fixing clip</th>
</tr>
</thead>
<tbody>
<tr>
<td>½&quot;-16 UNF-3A Part no. 560 315</td>
<td>11 (0.43)</td>
<td>0.32 (0.013)</td>
<td>Part no. 561 481</td>
</tr>
<tr>
<td>Material: Fluoroelastomer</td>
<td>Material: Steel, zinc plated</td>
<td>Material: Steel, zinc plated</td>
<td>Application: Used to secure sensor rods (Ø 10 mm (Ø 0.39 in.)) when using an U-magnet or block magnet</td>
</tr>
<tr>
<td>Durometer: 75 ± 5 Shore A</td>
<td>Operating temperature: -40…+204 °C (-40…+400 °F)</td>
<td>Material: Brass, non-magnetic</td>
<td></td>
</tr>
</tbody>
</table>

**Controlling design dimensions are in millimeters and measurements in ( ) are in inches**
4.6 Frequently ordered accessories for Start/Stop output – Additional options available in our Accessories Catalog

Cables

<table>
<thead>
<tr>
<th>FEP cable</th>
<th>Silicone cable</th>
</tr>
</thead>
<tbody>
<tr>
<td>Part no. 530 112</td>
<td>Part no. 530 113</td>
</tr>
<tr>
<td>Material: FEP jacket; black</td>
<td>Material: Silicone jacket; red</td>
</tr>
<tr>
<td>Features: Twisted pair, shielded, flexible, high thermal resistance, mostly oil &amp; acid resistant</td>
<td>Features: Twisted pair, shielded, highly flexible, halogen free, high thermical resistance</td>
</tr>
<tr>
<td>Cable Ø: 7.6 mm (0.3 in.)</td>
<td>Cable Ø: 7.2 mm (0.28 in.)</td>
</tr>
<tr>
<td>Cross section: 4 × 2 × 0.25 mm²</td>
<td>Cross section: 3 × 2 × 0.25 mm²</td>
</tr>
<tr>
<td>Bending radius: 8 – 10 × D (fixed installation)</td>
<td>Bending radius: 5 × D (fixed installation)</td>
</tr>
<tr>
<td>Operating temperature:</td>
<td>Operating temperature:</td>
</tr>
<tr>
<td>−100…+180 °C (−148…+356 °F)</td>
<td>−50…+180 °C (−58…+356 °F)</td>
</tr>
</tbody>
</table>

Controlling design dimensions are in millimeters and measurements in ( ) are in inches.

Cables

FEP cable
Part no. 530 112
Material: FEP jacket; black
Features: Twisted pair, shielded, flexible, high thermal resistance, mostly oil & acid resistant
Cable Ø: 7.6 mm (0.3 in.)
Cross section: 4 × 2 × 0.25 mm²
Bending radius: 8 – 10 × D (fixed installation)
Operating temperature: −100…+180 °C (−148…+356 °F)

Silicone cable
Part no. 530 113
Material: Silicone jacket; red
Features: Twisted pair, shielded, highly flexible, halogen free, high thermical resistance
Cable Ø: 7.2 mm (0.28 in.)
Cross section: 3 × 2 × 0.25 mm²
Bending radius: 5 × D (fixed installation)
Operating temperature: −50…+180 °C (−58…+356 °F)
5. Operation

5.1 Getting started

The sensor is factory-set to its order sizes and adjusted, i.e. the required output signal corresponds exactly to the selected stroke length.

**NOTICE**

**Observe during commissioning**

1. Before switching on for the first time, check the connection of the sensor carefully.
2. Position the magnet in the measuring range of the sensor during first commissioning and after replacement of the magnet.
3. Ensure that the sensor control system cannot be displaced in an uncontrolled way when switching on.
4. Ensure that the sensor is ready and in operation mode after switching on.

5.2 Programming and configuration

The functional diagram of the sensor with Start/Stop interface is shown in Fig. 17. The start pulse of the controller is acknowledged by the sensor with a stop pulse; the position measurement starts. At the end of the measurement the sensor generates a second stop pulse. The time between the start pulse and the second stop pulse is the travel time.

**Parameter upload**

The parameter upload function allows transfer of sensor parameters to the controller. It is easy to measure and store the sensor parameters given below using the same physical interface, without additional connections, via the communication mode to the controller.

**Technical data:**

- **Interface:** RS-422
- **Data format:** Serial, 4800 baud, 8 bit data

The diagram of the data transfer for parameter upload of the sensor with Start/Stop interface is shown in Fig. 18. The start pulse width has to be > 10 µs to start the parameter upload function. A start pulse width > 2.5 µs and < 10 µs is not permitted. The data is sent to the controller with the low bit first (one start bit “0”, one stop bit “1”, no parity).

![Diagram of data transfer for parameter upload](image)

The following parameters are transferred via parameter upload function:

1. **Gradient**
   - The gradient specifies the travelling speed of the measuring pulse. Gradient and travel time between start pulse and stop pulse are used to determine the position of the position magnet.
   - Position = gradient × travel time
   - The speed of the measuring pulse is approx. 2780 m/s (9.14 µs/inch.). The exact value is determined during final component checking and specified as a gradient on the sensor label.

2. **Offset**
   - The offset indicates the value of the position magnet’s position at span start. It is used as a reference value to detect when the stroke length is left and to adapt the position values.
   - Position = gradient × travel time – offset
   - **NOTICE** Check gradient after replacing the sensor to avoid errors in position measurement.

3. **Stroke length**
   - Indicates the useful measurement displacement of the sensor.

4. **Serial number**
   - Every sensor is provided with a unique serial number, which is printed on the sensor label and stored in the sensor.

5. **Manufacturer identification**
   - Due to the manufacturer identification, the controller can take manufacturer specific particularities into account.

6. **Status**
   - Provides information on the sensor status.
7. Minimum cycle time
The minimum cycle time specifies the time, which has to be between two consecutive start pulses of position measurement. The start pulse for each measurement is generated by the controller.

Data communication
As shown in Fig. 17 communication between controller and sensor is performed via the already provided connections. So the start lines are used for sending from the controller to the sensor, while the stop lines are used for receiving. For data exchange using the parameter upload function the start line is set to level High. The start pulse width has to be > 10 µs to ensure that the sensor switches over safely to the communication mode. Subsequently, the required command can be transmitted to the sensor.

NOTICE
Setting the start line to Low level is considered as a start bit of data transfer and treated accordingly by the sensor. Note that a bit combination which does not correspond to the controller command set is treated as a data fault and re-activates the Start/Stop operation (measuring mode). The occurrence of a data fault can be detected subsequently by a status request.

Read command | Code hex. | Transmitted bytes hex. | Note
--- | --- | --- | ---
Gradient | 0x55 | 4 | in cm/s
Offset | 0x57 | 4 | in µm
Stroke length | 0x59 | 4 | in mm
Serial number | 0x5D | 4 |
Manufacturer recognition | Temposonics | 0x61 | 4 | 0
Status | 0x5F | 4 |
Minimum cycle time | 0x73 | 4 | in µs
General commands
Stop communication | 0x3D | — |

Telegram formats
Read commands:
Data is transmitted from the sensor to the controller. For this purpose, the controller sends a request command and receives the required data, after the sensor has processed the command. Only after data transmission to the controller, the sensor is ready to receive and process further commands. The communication telegram looks like this:

1. Data request: E.g. “read gradient”
Controller → command 0x55 → sensor

2. Data reception: Output of gradient
(message with a length of 4 bytes)
Sensor → Byte 3 (High byte) → controller
Sensor → Byte 2 → controller
Sensor → Byte 1 → controller
Sensor → Byte 0 (Low byte) → controller

NOTICE
The High byte is sent first!

The pause time between bytes is approximately 6 ms.

Status:
The status command is an exception, since the command can be used to retrieve current sensor status information. After requesting the status, the controller can receive the following message:

1. Everything o.k.
Sensor → 0x00 00 00 00 → controller
The sensor did not detect an error.

2. Unknown command
Sensor → 0x00 00 00 AA → controller
An unknown command which is not mentioned in Fig. 19 was received by the sensor. This can be due to trouble on the data line or malfunction of the controller. In this case, the sensor sets the status to 0xAA, leaves the communication mode and starts operating in Start/Stop mode for position determination and position output. After restarting the communication mode, the status byte which is reset to 0x00 can be retrieved. Thus the controller realizes that cancellation is due to trouble.

3. Defective data set in EEPROM
Sensor → 0x00 00 00 FF → controller
When checking the EEPROM data set during start-up, divergence of the calculated checksum from the stored checksum was found. Consequently, there is a risk to use faulty data. If this should be the case, the status is set to 0xFF and the sensor must be re-adjusted. Therefore it is recommended to start a status request after switching on the supply voltage.
Terminale communication
Changing from the communication mode to the Start/Stop mode is performed by the command “terminating the communication”:

Sensor → 0x3D → controller

This command terminates the communication. The operation is continued with the operation in Start/Stop mode for position determination and position output.

6. Maintenance and troubleshooting

6.1 Error conditions, troubleshooting

<table>
<thead>
<tr>
<th>Error condition</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>Unknown command</td>
<td>Sensor sets the status to 0xAA</td>
</tr>
</tbody>
</table>

6.2 Maintenance

The required inspections need to be performed by qualified personnel according to IEC 60079-17/TRBS 1203. These inspections should include at least a visual inspection of the housing, associated electrical equipment entrance points, retention hardware and equipment grounding. Inside the Ex-atmosphere the equipment has to be cleaned regularly. The user determines the intervals for checking according to the environmental conditions present at the place of operation. After maintenance and repair all protective devices removed for this purpose must be refitted.

In case of equipment faults, remove the equipment. The inner parts cannot be maintained by the customer. In this case send the equipment to the manufacturer for inspection.

**NOTICE**

It is not allowed to open the sensor.

<table>
<thead>
<tr>
<th>Type of inspection</th>
<th>Visual inspection every 3 months</th>
<th>Close inspection every 6 months</th>
</tr>
</thead>
<tbody>
<tr>
<td>Visual inspection of the sensor for intactness, removal of dust deposits</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Check of entire system</td>
<td>User’s responsibility</td>
<td></td>
</tr>
</tbody>
</table>

Fig. 22: Schedule of inspection

6.3 Repair

Repairs on the sensor may be performed only by Temposonics or an explicitly authorized body.

6.4 List of spare parts

No spare parts are available for this sensor.

6.5 Transport and storage

The conditions of transport and storage of the sensor match the operating conditions mentioned in this document.

7. Removal from service/dismantling

The product contains electronic components and must be disposed of in accordance with the local regulations.

**Maintenance** Defines a combination of any actions carried out to retain an item in, or restore it to, conditions in which it is able to meet the requirements of the relevant specification and perform its required functions.
8. Technical data of Temposonics® ET

<table>
<thead>
<tr>
<th>Output</th>
<th>Start/Stop</th>
<th>RS-422 differential signal</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Serial parameter upload available for: Stroke length, offset, gradient, status, serial number and manufacturer number</td>
</tr>
<tr>
<td>Measured value</td>
<td>Position</td>
<td></td>
</tr>
</tbody>
</table>

**Measurement parameters**

<table>
<thead>
<tr>
<th>Resolution</th>
<th>Controller dependent</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cycle time</td>
<td>Controller and stroke length dependent</td>
</tr>
<tr>
<td></td>
<td>Recommendation: Stroke length ≤ 1000 mm ≤ 2000 mm ≤ 3000 mm</td>
</tr>
<tr>
<td>Linearity</td>
<td>≤ ±0.02 % F.S. (minimum ±60 μm)</td>
</tr>
<tr>
<td>Repeatability</td>
<td>≤ ±0.005 % F.S. (minimum ±20 μm) typical</td>
</tr>
</tbody>
</table>

**Operating conditions**

<table>
<thead>
<tr>
<th>Operating temperature</th>
<th>−40…+105 °C (−40…+221 °F)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Humidity</td>
<td>90 % relative humidity, no condensation</td>
</tr>
<tr>
<td>Ingress protection</td>
<td>With FEP cable (part no. 530 112): IP66</td>
</tr>
<tr>
<td></td>
<td>With silicone cable (part no. 530 113): IP68 (2 bar (29 psi) @ 30 min)</td>
</tr>
<tr>
<td>Shock test</td>
<td>100 g (single shock), IEC standard 60068-2-27</td>
</tr>
<tr>
<td>Vibration test</td>
<td>20 g/10…2000 Hz, IEC 60068-2-6 (excluding resonant frequencies)</td>
</tr>
<tr>
<td>EMC test</td>
<td>Electromagnetic emission according to EN 61000-6-3</td>
</tr>
<tr>
<td></td>
<td>Electromagnetic immunity according to EN 61000-6-2</td>
</tr>
<tr>
<td></td>
<td>The ET sensors fulfill the requirements of the EMC directives 2014/30/EU, UKSI 2016 No. 1091 and TR CU 020/2011</td>
</tr>
<tr>
<td>Operating pressure</td>
<td>Up to 350 bar (5076 psi)</td>
</tr>
<tr>
<td>Magnet movement velocity</td>
<td>Any</td>
</tr>
</tbody>
</table>

**Design/Material**

| Sensor electronics housing/ Flange | Stainless steel 1.4305 (AISI 303); option: Stainless steel 1.4404 (AISI 316L) |
| Sensor rod                        | Stainless steel 1.4306 (AISI 304L); option: Stainless steel 1.4404 (AISI 316L) |
| RoHS compliance                   | The used materials are compliant with the requirements of EU directive 2011/65/EU and EU regulation 2015/863 as well as UKSI 2012 No. 3032 |
| Stroke length                     | 50…3000 mm (2…118 in.) |

**Mechanical mounting**

| Mounting position               | Any |

**Mounting instruction**

Please consult the technical drawings on page 8

**Electrical connection**

| Connection type                | Cable outlet |
| Operating voltage              | +24 VDC (−15/+20 %) |
| Ripple                         | ≤ 0.28 Vpp |
| Current consumption            | Maximum 50 mA |
| Dielectric strength            | 700 VDC (DC ground to machine ground) |
| Polarity protection            | Up to −30 VDC |
| Overvoltage protection         | Up to ≤ 32 VDC |

3/ With position magnet # 251 416-2

4/ If there is contact between the moving magnet including the magnet holder and the sensor rod, make sure that the maximal speed of the moving magnet is ≤ 1 m/s (Ex requirement due to ESD [Electro Static Discharge])
Temposonics® E-Series ET Start/Stop ATEX/UK Ex/IECEx/CEC/NEC/CCC Certified
Operation Manual

CERTIFICATION

II 3G Ex nC IIC T4 Gc
II 3D Ex tc IIIIC T130 °C Dc
Class I/II/III Div 2 T4 ABCDFG
   Class I Zone 2 T4 IIC
   Zone 22 AEx tc T4 IIIIC Dc
   Ex tc IIIIC T130°C Dc IP66/IP68
Ex nC IIC T4 Gc
Ex tD A22 IP66/IP68 T130°C
−40 °C ≤ Ta ≤ 105 °C; Type: 4X; IP66/IP68

Fig. 23: Certification of Temposonics® ET (version A and E)
9. Appendix

Safety declaration

Dear Customer,
If you return one or several sensors for checking or repair, we need you to sign a safety declaration. The purpose of this declaration is to ensure that the returned items do not contain residues of harmful substances and/or that people handling these items will not be in danger.

Tempsonics order number: __________________________
Serial number(s): __________________________________
Sensor type(s): ____________________________________________
Sensor length(s):___________________________________________

The sensor has been in contact with the following materials:

Do not specify chemical formulas.
Please include safety data sheets of the substances, if applicable.

In the event of suspected penetration of substances into the sensor, consult Tempsonics to determine measures to be taken before shipment.

Short description of malfunction:

Corporate information

Company:______________________________________________
Address:______________________________________________
____________________________________________________

Contact partner

Phone:______________________________________________
Fax:______________________________________________
Email:______________________________________________

We hereby certify that the measuring equipment has been cleaned and neutralized.
Equipment handling is safe. Personnel exposure to health risks during transport and repair is excluded.

______________________________
Stamp

______________________________
Signature

______________________________
Date

Temposonics GmbH & Co.KG
Tel. +49 2351/95 87-0
Auf dem Schüffel 9
Fax. +49 2351/56 49 1
58513 Lüdenscheid
info.de@temposonics.com
Germany
www.temposonics.com
10. Declaration of conformity

**EU Declaration of Conformity**

Temposonics declares as manufacturer in sole responsibility that the position sensor type

Temposonics
ET-x-xxxxx-xxx-1-A-Axx-x
ET-x-xxxxx-xxx-1-E-Axx-x
ET-x-xxxxx-xxx-1-A-Vxx-x
ET-x-xxxxx-xxx-1-E-Vxx-x
ET-x-xxxxx-xxx-1-A-Sxxxxxx
ET-x-xxxxx-xxx-1-E-Sxxxxxx

comply with the regulations of the following European Directives:

2014/30/EU Electromagnetic Compatibility

2014/34/EU Equipment and protective systems for use in potentially explosive atmospheres

2011/65/EU Restriction of the use of hazardous substances in electrical and electronic equipment

Applied harmonized standards:
EN IEC 60079-0 :2018
EN IEC 60079-15 :2010
EN 60079-31 :2014
EN 61000-6-2 :2005
EN 61000-6-4 :2007+A1 :2011

Manufature test report: 605895

Marking:
- II 3G Ex nC IIC T4 Gc
- II 3D Ex tc IIIC T130°C Dc

Lüdenscheid, 17 Mar. 2023

Dr.-Ing. Eugen Davidoff
Approvals Manager

**EU Konformitätserklärung**

Temposonics erklärt als Hersteller in alleiniger Verantwortung, dass der Positionssensor Typ

Temposonics
ET-x-xxxxx-xxx-1-A-Axx-x
ET-x-xxxxx-xxx-1-E-Axx-x
ET-x-xxxxx-xxx-1-A-Vxx-x
ET-x-xxxxx-xxx-1-E-Vxx-x
ET-x-xxxxx-xxx-1-A-Sxxxxxx
ET-x-xxxxx-xxx-1-E-Sxxxxxx
den Vorschriften folgender Europäischen Richtlinien entsprechen:

2014/30/EU Elektromagnetische Verträglichkeit

2014/34/EU Geräte und Schutzsysteme zur Verwendung in explosionsgefährdeten Bereichen

2011/65/EU Beschränkung der Verwendung gefährlicher Stoffe in Elektro- und Elektronikgeräten

Angewandte harmonisierte Normen:
EN IEC 60079-0 :2018
EN IEC 60079-15 :2010
EN 60079-31 :2014
EN 61000-6-2 :2005
EN 61000-6-4 :2007+A1 :2011

Hersteller-Prüfbericht: 605895

Kennzeichnung:
- II 3G Ex nC IIC T4 Gc
- II 3D Ex tb IIIC T130°C Dc

**Déclaration UE de Conformité**

Temposonics déclare en qualité de fabricant sous sa seule responsabilité que les capteurs de position de type

Temposonics
ET-x-xxxxx-xxx-1-A-Axx-x
ET-x-xxxxx-xxx-1-E-Axx-x
ET-x-xxxxx-xxx-1-A-Vxx-x
ET-x-xxxxx-xxx-1-E-Vxx-x
ET-x-xxxxx-xxx-1-A-Sxxxxxx
ET-x-xxxxx-xxx-1-E-Sxxxxxx
sont conformes aux prescriptions des directives européennes suivantes:

2014/30/EU Compatibilité électromagnétique

2014/34/EU Appareils et systèmes de protection à être utilisés en atmosphères explosibles

2011/65/EU Limitation de l’utilisation de substances dangereuses dans les équipements électriques et électroniques

Normes harmonisées appliquées:
EN IEC 60079-0 :2018
EN IEC 60079-15 :2010
EN 60079-31 :2014
EN 61000-6-2 :2005
EN 61000-6-4 :2007+A1 :2011

Rapport d’essai du fabricant: 605895

Marquage:
- II 3G Ex nC IIC T4 Gc
- II 3D Ex tb IIIC T130°C Dc
EU Declaration of Conformity

Temposonics declares as manufacturer in sole responsibility that the position sensor type

Temposonics
ET-x-xxxxx-xxx-1-N-Axx-x
ET-x-xxxxx-xxx-1-N-Vxx-x
ET-x-xxxxx-xxx-1-N-Sxxxxx

comply with the regulations of the following European Directives:

2014/30/EU Electromagnetic Compatibility
2011/65/EU Restriction of the use of hazardous substances in electrical and electronic equipment

Applied harmonized standards:
EN 61000-6-2 :2005
EN 61000-6-4 :2007+A1 :2011

Luedenscheid, 17 Mar. 2023

Dr.-Ing. Eugen Davidoff
Approvals Manager

EU Konformitätserklärung

Temposonics erklärt als Hersteller in alleiniger Verantwortung, dass der Positionssensor Typ

Temposonics
ET-x-xxxxx-xxx-1-N-Axx-x
ET-x-xxxxx-xxx-1-N-Vxx-x
ET-x-xxxxx-xxx-1-N-Sxxxxx
den Vorschriften folgender Europäischen Richtlinien entsprechen:

2014/30/EU Elektromagnetische Verträglichkeit
2011/65/EU Beschränkung der Verwendung gefährlicher Stoffe in Elektro- und Elektronikgeräten

Angewandte harmonisierte Normen:
EN 61000-6-2 :2005
EN 61000-6-4 :2007+A1 :2011

Luedenscheid, 17 Mar. 2023

Dr.-Ing. Eugen Davidoff
Approvals Manager

Déclaration UE de Conformité

Temposonics déclare en qualité de fabricant sous sa seule responsabilité que les capteurs de position de type

Temposonics
ET-x-xxxxx-xxx-1-N-Axx-x
ET-x-xxxxx-xxx-1-N-Vxx-x
ET-x-xxxxx-xxx-1-N-Sxxxxx

sont conformes aux prescriptions des directives européennes suivantes:

2014/30/EU Compatibilité électromagnétique
2011/65/EU Limitation de l’utilisation de substances dangereuses dans les équipements électriques et électroniques

Normes harmonisées appliquées:
EN 61000-6-2 :2005
EN 61000-6-4 :2007+A1 :2011

Luedenscheid, 17 Mar. 2023

Dr.-Ing. Eugen Davidoff
Approvals Manager
Temposonics declares as manufacturer in sole responsibility that the position sensor type

den Vorschriften folgender UK Richtlinien entsprechen:

UKSI 2016:1091 Electromagnetic Compatibility
UKSI 2016:1107 The Equipment and Protective Systems Intended for Use in Potentially Explosive Atmospheres
UKSI 2012:3032 Restriction of the use of hazardous substances in electrical and electronic equipment (as amended)

Angewandte harmonisierte zugelassene Normen:
EN IEC 60079-0:2018
EN IEC 60079-15:2010
EN 60079-31:2014
EN 61000-6-2:2005
EN 61000-6-4:2007+A1:2011

Hersteller-Prüfbericht: 605895

Markung:
II 3G Ex nc IIC T4 Gc
II 3D Ex tc IIIC T130°C Dc

Luedenscheid, 10 Mar. 2023

Dr.-Ing. Eugen Davidoff
Approvals Manager
UK Declaration of Conformity

Temposonics declares as manufacturer in sole responsibility that the position sensor type

Temposonics
ET-x-xxxxx-xxx-1-N-xxxx
ET-x-xxxxx-xxx-1-N-Vxxxx
ET-x-xxxxx-xxx-1-N-5xxxx

comply with the regulations of the following UK Directives:

UKSI 2016 :1091 Electromagnetic Compatibility
UKSI 2012 :3032 Restriction of the use of hazardous substances in electrical and electronic equipment (as amended)

Applied harmonized approved standards:

EN 61000-6-2 :2005
EN 61000-6-4 :2007+A1 :2011

Luedenscheid, 10 Mar. 2023

Dr.-Ing. Eugen Davidoff
Approvals Manager