

Data Sheet

T-Series – TH SSI

Magnetostrictive Linear Position Sensors

- ATEX/UK Ex/IECEx/CEC/NEC/KCs/CCC/PESO certified/Japanese approval
- Continuous operation under harsh industrial conditions
- Flameproof/Explosionproof/Increased safety



MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics[®] position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and a supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.



Fig. 1: Time-of-flight based magnetostrictive position sensing principle

TH SENSOR

Robust, non-contact and wear free, the Temposonics[®] linear position sensors provide best durability and accurate position measurement solutions in harsh industrial environments. The position measurement accuracy is tightly controlled by the quality of the waveguide which is manufactured by Temposonics. The position magnet is mounted on the moving machine part and travels contactlessly over the sensor rod with the built-in waveguide.

The TH sensor is extremely robust and ideal for continuous operation under harsh industrial conditions. T-Series sensors are certified for hazardous areas in Zone 0/1, Zone 1, Zone 2, Zone 21 and Zone 22 for Europe (ATEX), the English, Welsh, Scottish (UK Ex), the global (IECEx), the South Korean (KCs), the Chinese (CCC), the Indian (PESO), the Japanese market as well as for use in Class I, II, III, Division 1, Division 2 for Canada (CEC) and USA (NEC). The sensor electronics housing contains the active signal conditioning and a complete integrated electronics interface. The sensor rod is capable of withstanding high pressures such as those found in hydraulic cylinders. Furthermore the sensor is also suitable for petro chemical plants and caustic environments. In addition the sensor meets the ingress protection IP66/IP67/IP68 (100 m for 7 days)/IP69 and NEMA 4 (for sensor assembly in stainless steel 1.4404 (AISI 316L)).



Fig. 2: Typical application: Tank systems

TECHNICAL DATA

Output	
Interface	SSI (Synchronous Serial Interface) – differential signal in SSI standard (RS 422)
Data format	Binary or gray, optional parity and error bit or temperature of sensor electronics
Data length	832 bit
Data transmission rate	70 kBaud 1 1 MBaud, depending on cable length:Cable length< 3 m< 50 m< 100 m< 200 m< 400 mBaud rate1 MBd< 400 kBd
Measured value	Position, differentiation measurement, velocity, temperature of sensor electronics
Measurement parameters	
Resolution	Position: 0.5 μm, 1 μm, 2 μm, 5 μm, 10 μm, 20 μm, 50 μm, 100 μm/ Velocity over 10 measured values: 0.1 mm/s (at 1 ms cycle time)
Cycle time	Stroke length 300 mm 750 mm 1000 mm 2000 mm 5000 mm Measurement rate 3.7 kHz 3.0 kHz 2.3 kHz 1.2 kHz 0.5 kHz
Linearity ²	< ±0.01 % F.S. (minimum ±40 µm)
Repeatability	$< \pm 0.001$ % F.S. (minimum $\pm 2.5 \ \mu$ m) typical
Hysteresis	< 4 µm typical
Temperature coefficient	< 15 ppm/K typical
Operating conditions	
Operating temperature	-40+75 °C (-40+167 °F)
Humidity	90 % relative humidity, no condensation
Ingress protection	IP66/IP67/IP68 (100 m for 7 days)/IP69 and NEMA 4 (for sensor assembly in stainless steel 1.4305 (AISI 303)) or NEMA 4X (for sensor assembly in stainless steel 1.4404 (AISI 316L)) (if appropriate pipes, glands, etc. are connected properly)
Shock test	100 g/6 ms according to IEC 60068-2-27
Repeated shock events	160 g/2 ms according to IEC 60068-2-27 (for shock improved option A, see order code for Operating Voltage on page 13)
Vibration test	15 g/102000 Hz according to IEC 60068-2-6 (excluding resonant frequencies)
EMC test	Electromagnetic emission according to EN IEC 61000-6-3 Electromagnetic immunity according to EN IEC 61000-6-2 The TH sensors fulfill the requirements of the EMC directives 2014/30/EU, UKSI 2016 No. 1091
Operating pressure	350 bar static (5076 psi static)
Magnet movement velocity ³	Any
Design/Material	
Sensor electronics housing	Stainless steel 1.4305 (AISI 303); option: Stainless steel 1.4404 (AISI 316L)
Flange	See "Table 1: TH rod sensor threaded flange type references" on page 7
Sensor rod	Stainless steel 1.4306 (AISI 304L); option: Stainless steel 1.4404 (AISI 316L)
RoHS compliance	The used materials are compliant with the requirements of EU directive 2011/65/EU and EU regulation 2015/863 as well as UKSI 2012 No. 3032
Stroke length	257620 mm (1300 in.) (for shock improved option A , see order code on page 13: 253760
Mechanical mounting	mm (1148 m.))
Meenancear mounting	A.m.
wounting position	Any
Mounting instruction	Please consult the technical drawings and the operation manual (document number: $\frac{551902}{551902}$)

See next page for "Electrical connection"

1/ With standard one shot of 16 μs

2/ With position magnet # 201 542-2

3/ If there is contact between the moving magnet including the magnet holder and the sensor rod, make sure that the maximum speed of the moving magnet is ≤ 1 m/s (Safety requirement due to ESD [Electro Static Discharge])

Temposonics® TH SSI Data Sheet

Electrical connection	
Connection type	T-Series terminal
Operating voltage	+24 VDC (-15/+20 %)
Ripple	$\leq 0.28 \text{ V}_{pp}$
Current consumption	100 mA typical
Dielectric strength	700 VDC (DC ground to machine ground)
Polarity protection	Up to -30 VDC
Overvoltage protection	Up to 36 VDC

CERTIFICATIONS

Certification required	Version E	Version D	Version G	Version N
IECEx/ATEX (IECEx: Global market; ATEX: Europe)	Ex db eb IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 –40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	No hazardous area approval
UK Ex (England, Wales and Scotland)	Ex db eb IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 −40 °C ≤ Ta ≤ 75 °C	Ex db IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	No hazardous area approval
NEC (USA)	_	_	Explosionproof Class I Div. 1 Groups A, B, C, D T4 Class II/III Div. 1 Groups E, F, G T130°C -40 °C \leq Ta \leq 75 °C Flameproof Class I Zone 0/1 AEx d IIC T4 Class II/III Zone 21 AEx tb IIIC T130°C -40 °C \leq Ta \leq 75 °C	No hazardous area approval
CEC (Canada)	_	_	Explosionproof Class I Div. 1 Groups B, C, D T4 Class II/III Div. 1 Groups E, F, G T130°C -40 °C \leq Ta \leq 75 °C Flameproof Class I Zone 0/1 Ex d IIC T4 Ga/Gb Class II/III Zone 21 Ex tb IIIC T130°C Db -40 °C \leq Ta \leq 75 °C	No hazardous area approval
Japanese approval	Ex d e IIC T4 Ga/Gb Ex t IIIC T130°C Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Ga/Gb Ex t IIIC T130°C Db Zone 0/1, Zone 21 −40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Ga/Gb Ex t IIIC T130°C Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	No hazardous area approval
CCC (China)	Ex d e IIC T4 Gb Ex tD A21 IP66/67 T130°C Zone 1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex d IIC T4 Gb Ex tD A21 IP66/67 T130°C Zone 1, Zone 21 -40 °C \leq Ta \leq 75 °C	Ex d IIC T4 Gb Ex tD A21 IP66/67 T130°C Zone 1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	No hazardous area approval
PESO (India)	Ex db eb IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C ≤ Ta ≤ 75 °C	Ex db eb IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	Ex db eb IIC T4 Ga/Gb Ex tb IIIC T130°C Ga/Db Zone 0/1, Zone 21 -40 °C \leq Ta \leq 75 °C	No hazardous area approval

Fig. 3: Certifications

TECHNICAL DRAWING



Fig. 4: Temposonics® TH with ring magnet

CONNECTION OPTIONS



Fig. 5: Temposonics[®] TH connection options

Threaded flange type	Description	Threaded flange
F	Threaded flange with flat-face Stainless steel 1.4404 (AISI 316L)	³ ⁄4"-16 UNF-3A
G	Threaded flange with raised-face Stainless steel 1.4404 (AISI 316L)	3⁄4"-16 UNF-3A
М	Threaded flange with flat-face Stainless steel 1.4305 (AISI 303)	M18×1.5-6g
N	Threaded flange with raised-face Stainless steel 1.4305 (AISI 303)	M18×1.5-6g
S	Threaded flange with flat-face Stainless steel 1.4305 (AISI 303)	3⁄4"-16 UNF-3A
т	Threaded flange with raised-face Stainless steel 1.4305 (AISI 303)	3⁄4"-16 UNF-3A
W	Threaded flange with flat-face Stainless steel 1.4404 (AISI 316L)	M18×1.5-6g

Table 1: TH rod sensor threaded flange type references

ZONE CLASSIFICATION



Fig. 6: Temposonics® TH Zone classification

NOTICE

Seal sensor according to ingress protection IP67 between Zone 0 and Zone 1.

CONNECTOR WIRING

Version D & G suitable for connection types: C01, C10, N01, N10					
Signal + power suppl	У				
Terminal	Pin	Function			
	1	Data (-)			
	2	Data (+)			
	3	Clock (+)			
	4	Clock (-)			
	5	+24 VDC (-15/+20 %)			
6]0	6	DC Ground (0 V)			
	7	Cable shield			

Fig. 7: TH (version D & G) wiring diagram (2.5 mm² conductor)

Version E & N suitable for connection types: C01, C10, M01, M10, N01, N10				
Signal + power supply				
Terminal	Pin	Function		
	1	Data (–)		
	2	Data (+)		
	3	Clock (+)		
	4	Clock (-)		
	5	+24 VDC (-15/+20 %)		
	6	DC Ground (0 V)		
	7	Cable shield		

Fig. 8: TH (version E & N) wiring diagram (1.5 mm² conductor)

FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Guide 🗍 551444



Controlling design dimensions are in millimeters and measurements in () are in inches

- 4/ Be sure that the float specific gravity is at least 0.05 less than that of the measured liquid as a safety margin at ambient temperature
 - For interface measurement: A minimum of 0.05 specific gravity differential is required between the upper and lower liquids
- When the magnet is not shown, the magnet is positioned at the center line of float
 An offset weight is installed in the float to bias or tilt the float installed on the sensor

 An offset weight is installed in the float to bias or tilt the float installed on the sensor tube. So the float remains in contact with the sensor tube at all times and guarantees permanent potential equalization of the float. The offset is required for installations that must conform to hazardous location standards



Controlling design dimensions are in millimeters and measurements in () are in inches

- 5/ Be sure that the float specific gravity is at least 0.05 less than that of the measured liquid as a safety margin at ambient temperature
 - For interface measurement: A minimum of 0.05 specific gravity differential is required between the upper and lower liquids
 - . When the magnet is not shown, the magnet is positioned at the center line of float
- An offset weight is installed in the float to bias or tilt the float installed on the sensor tube. So the float remains in contact with the sensor tube at all times and guarantees permanent potential equalization of the float. The offset is required for installations that must conform to hazardous location standards
- 6/ Standard float that can be expedited



Manuals, Software & 3D Models available at: www.temposonics.com

Controlling design dimensions are in millimeters and measurements in () are in inches

7/ The programming tool is not approved for use in hazardous environments

ORDER CODE

a Sensor model



T	H Ro	d			
b	Design				
En	closure	Tvpe	4:		
TH	rod sen	sor v	vith	housing ma	aterial stainless steel 1.4305
(Al	SI 303)	and ı	rod I	material sta	ainless steel 1.4306 (AISI 304L)
М	Thread	ed fla	ange	with flat-fa	ice (M18×1.5-6g)
Ν	Thread	ed fla	ange	with raised	l-face (M18×1.5-6g)
S	Thread	ed fla	ange	with flat-fa	ice (¾"-16 UNF-3A)
T	Thread	ed fla	ange	with raised	I-face (¾"-16 UNF-3A)
En	closure	Туре	4X:	h	terial stainlass staal 4 4404
іп (АІ	SI 316L) and	rod	material s	tainless steel 1.4404 (AISI 316L
F	Thread	ed fla	ange	with flat-fa	ice (¾"-16 UNF-3A)
G	Thread	ed fla	ange	with raised	1-face (¾"-16 UNF-3A)
W	Thread	ed fla	ange	with flat-fa	ice (M18×1.5-6g)
C	Stroke	leng	th		
X	XX	X	М	0025762	20 mm
Sta	indard s	troke	len	gth (mm)	Ordering steps
	25 50)0 mr	n		5 mm
50	0075	50 mr	n		10 mm
1	50100	00 mr	n		25 mm
100	00250	JU mr	n		50 mm
250	00500	JU mr	n		100 mm
50	00762	20 mr	n 	004.0.00	250 mm
X	XX	X	U	001.030	U.U IN.
518	indard s	Iroke	Ien	gtn (In.)	Urdering steps
0(0 20	111. in			0.2 III.
20	030	111. in			0.4 III.
30	040	in. in			1.0 Iff.
40	0100	III. in			2.0 III.
100	0200	iii.			4.0 III.
200	0300 n Stand	III. ard ef	rok	longthe or	IU.U III. o availablo:
m	Non Standard stroke lengths are available; must be encoded in 5 mm/0.1 in. increments.				

			· ·
d	Co	nnec	ction type
C	0	1	Side connection with thread ½"-14 NPT (All versions)
C	1	0	Top connection with thread ½"-14 NPT (All versions)
Μ	0	1	Side connection with thread M16×1.5-6H (Version E & N)
Μ	1	0	Top connection with thread M16×1.5-6H (Version E & N)
N	0	1	Side connection with thread M20×1.5-6H (All versions)
N	1	0	Top connection with thread M20×1.5-6H (All versions)

e	Operating voltage
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1	+24	VDC	(-15/	+20	%)
---	-----	-----	-------	-----	----

A +24 VDC (-15/+20 %) includes shock improved option stroke length 25...3760 mm (1...148 in.)

f	Version (see "Certifications" on page 5 for further information)
D	Ex db and Ex tb (A/F 55)
Ε	Ex db eb and Ex tb (A/F 55)
G	Ex db and Ex tb (A/F 60) <u>US & CA approval:</u> Explosionproof (XP) (Note: Group A is not available for Canada)
N	Not approved
g	Functional safety type
N	Not approved

- h Additional option type
- N None

i See next page

i	Output	i Output (continued)	
S (17) (18) (19) (20) (21) (22) (23) (24) (25)	Measurement contents (optional: Box no. 23)	
= 5	Synchronous Serial Interface	Note: Choose "9" in box no. 21 and 22	
Da	ta length (box no. 17)	1 Position measurement	
1	25 bit	2 Differentiation measurement ⁸	
2	24 bit	3 Velocity measurement	
3	26 bit	4 Position measurement + temperature measurement	
Ou	tput format (box no. 18)	(only with data length = 24 bit)	
В	Binary	5 Differentiation measurement ⁸ + temperature measurement	
G	Gray	(only with data length = 24 bit)	
Re	solution (box no. 19)	6 Velocity measurement + temperature measurement	
1	0.005 mm	(only with data length = 24 bit)	
2	0.01 mm	Direction and sync. mode (optional: Box no. 24) Note: Choose "9" in hox no. 21 and 22	
3	0.05 mm	1 Measuring direction forward, asynchronous mode	
4	0.1 mm	2 Measuring direction forward, synchronous mode 1	
5	0.02 mm	3 Measuring direction forward, synchronous mode 2	
6	0.002 mm	Measuring direction forward, synchronous mode 3	
8	0.001 mm	5 Measuring direction reverse, asynchronous mode	
9	0.0005 mm	6 Measuring direction reverse, synchronous mode 1	
Fil	tering performance (box no. 20)	7 Measuring direction reverse, synchronous mode 7	
Α	No filter + error delay (4 cycles)	Measuring direction reverse, synchronous mode 2	
C	No filter + error delay (8 cycles)	Diagnostics (ontional: Boy no. 25)	
1	Standard (no filters)	Note: Choose "9" in box no. 21 and 22	
8	Noise reduction filter (8 measurements)	0 No further options	
D	No filter + error delay (10 cycles)	2 Additional alarm bit + parity even bit	
G	Noise reduction filter (8 measurements) + error delay (10 cycles)	(not available for temperature output, only with data length = 24	l bit)
K	Peak reduction filter (8 measurements)		
Ν	Peak reduction filter (8 measurements) + error delay (10 cycles)	107105	
Si	jnal options (box no. 21, 22)	NOTICE	
0	0 Measuring direction forward, asynchronous mode	• The minimum allowed distance between magnets (i.e. front fa	ce
0	1 Measuring direction reverse, asynchronous mode	 Use magnets of the same type for multi-position measurement 	ıt.
0	2 Measuring direction forward, synchronous mode 1		

DELIVERY

Sensor

Accessories have to be ordered separately

Manuals, Software & 3D Models available at: www.temposonics.com

0 5 Measuring direction forward, asynchronous mode, bit 25 = alarm, bit 26 = parity even

9 9 Write "9" in box no. 21 and 22 for using further combinations in boxes 23, 24, 25



UNITED STATES Temposonics, LLC Americas & APAC Region	3001 Sheldon Drive Cary, N.C. 27513 Phone: +1 919 677-0100 E-mail: info.us@temposonics.com	Document Part Number 551950 Revision E (EN) 04/2023
GERMANY Temposonics GmbH & Co. KG EMEA Region & India	Auf dem Schüffel 9 58513 Lüdenscheid Phone: +49 2351 9587-0 E-mail: info.de@temposonics.com	
ITALY Branch Office	Phone: +39 030 988 3819 E-mail: info.it@temposonics.com	
FRANCE Branch Office	Phone: +33 6 14 060 728 E-mail: info.fr@temposonics.com	
UK Branch Office	Phone: +44 79 21 83 05 86 E-mail: info.uk@temposonics.com	
SCANDINAVIA Branch Office	Phone: + 46 70 29 91 281 E-mail: info.sca@temposonics.com	
CHINA Branch Office	Phone: +86 21 3405 7850 E-mail: info.cn@temposonics.com	
JAPAN Branch Office	Phone: +81364161063 E-mail: info.jp@temposonics.com	

temposonics.com

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