Temposonics
AN AMPHENOL COMPANY

Data Sheet

L-Series Analog + Digital

Magnetostrictive Linear Position Sensors

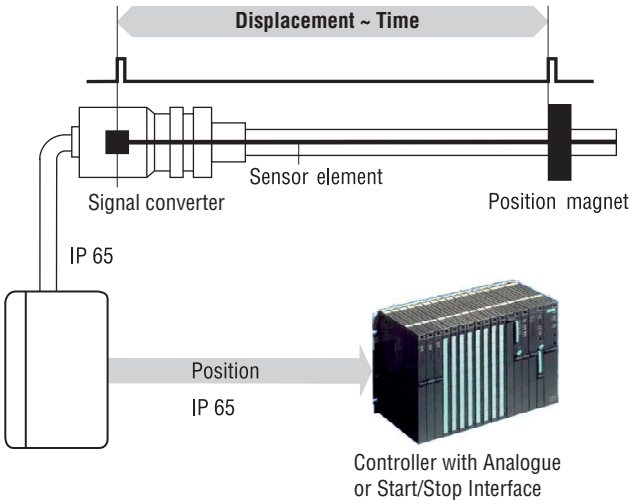
Document Part No.
05012010



A Compact Sensor for Hydro Cylinders

- Absolute Sensor
- Non-contact Measurement
- Modular Construction
- Stable Design
- Highest Durability
- Measuring Range: 50 - 5000 mm
- Linearity: Better 0,02 %
- Repeatability: 0,001 %
- Direct Analog Output (V/mA): 100% field adjustable
- Digital Pulse Output, Start-Stop

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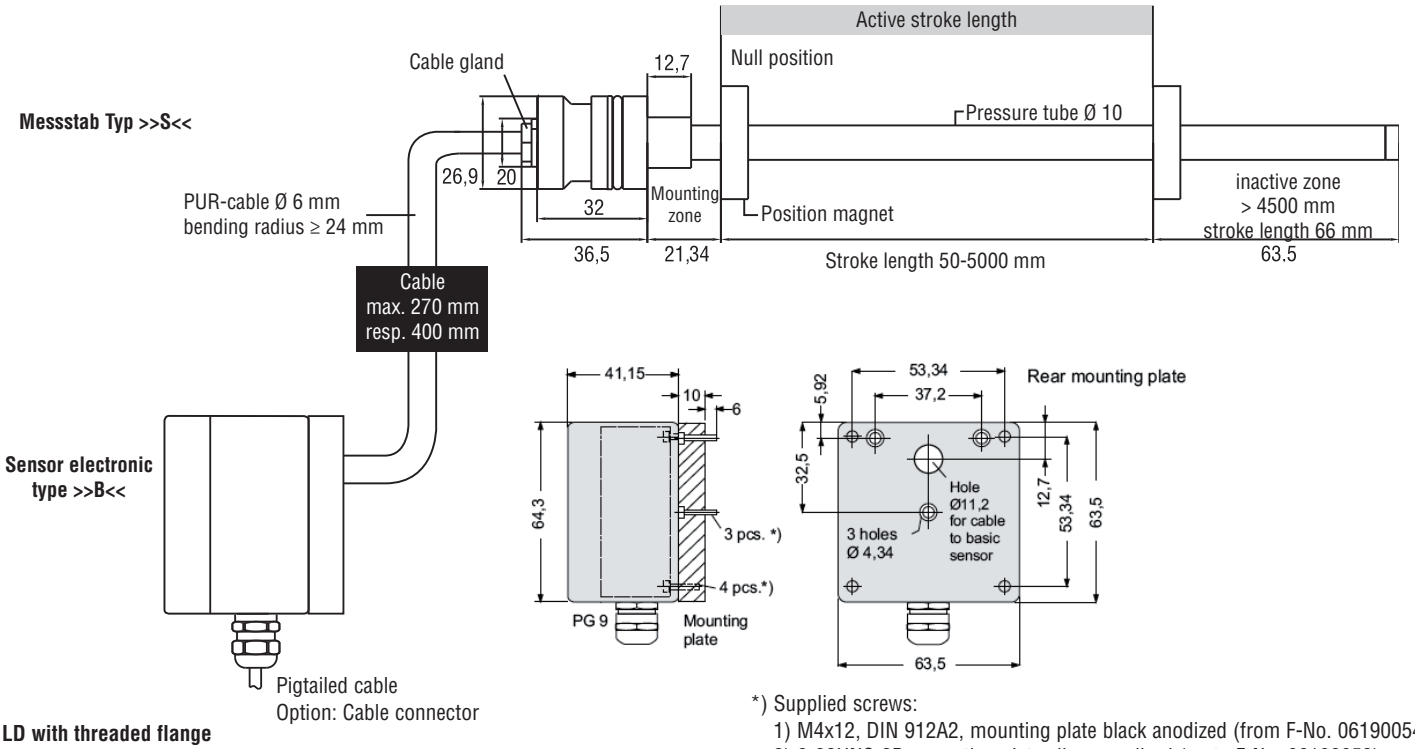


The absolute Temposonics linear position sensors are based on the Temposonics developed magnetostrictive measurement principle. That combines various magneto-mechanical effects and uses the physical hight precise speed-measurement of an ultrasonic wave (torsion pulse in its sensor element) for position detecting. The integral signal processing transforms the measurements into analogue or digital standardized outputs.
The *contactless* principle - an external movable magnet marks the position - eliminates the wear, noise and erroneous signal problems and guarantees the best durability without any recalibration.

Measured Variables	Displacement
Measuring Range	50 - 5000 mm
Output	Voltage: 0...10 VDC or 10...0 VDC (Minimum load: > 5 kOhm) Current: 4(0)...20 mA or 20...4(0) mA (Min/Max. 0 / 500 Ohm) Start/Stop pulse: RS422 Differential signal
Adjustment of NULL and SPAN	Analogue: 100% of measuring range (F.S.)
Resolution	Analogue: Infinite, restricted by output ripple Digital: 0,1 mm; 0,01 mm (controller depending)
Linearity	< ± 0,02 % F.S. (Minimum ± 50 µm)
Repeatability	< ± 0,001 % F.S.
Update Frequency	Analogue: 1kHz / Digital: controller dependent
Connection Type	Cable outlet
Input Voltage	24 VDC (-15 / +20 %)
Current Drain	100 mA typical
Ripple	< 1 % peak to peak
Temperature Coefficient	< 40 ppm/ °C
Electric Strength	500 V (DC ground to machine ground)
Operating Temperature	-40 °C...+75 °C
Dew Point, Humidity	90 % rel. humidity, no condensation
EMV-Test	Electromagnetic emission EN 50081-2; Electromagnetic immunity EN 50082-2 EN 6100-4-2/3/4/6 Level 3/4 Criteria A, LD-sensor installed in a ground metal housing
Shockrating	100 g, 6 ms / IEC-Standard 68-2-27
Vibration Rating	10 g, 10 - 2000 Hz / IEC-Standard 68-2-6
Mounting	Any orientation
Magnet speed	Any
Sensor rod + flange	Stainless steel 1.4301 / AISI 304
- Pressure Rating	350 bar, 700 bar peak pressure
Sensor Electronic Housing	Aluminium diecasting housing
Sealing	IP 65
Sensor Installation	Fitting flange or thread M18 x 1,5
Magnet Type	Ring magnet

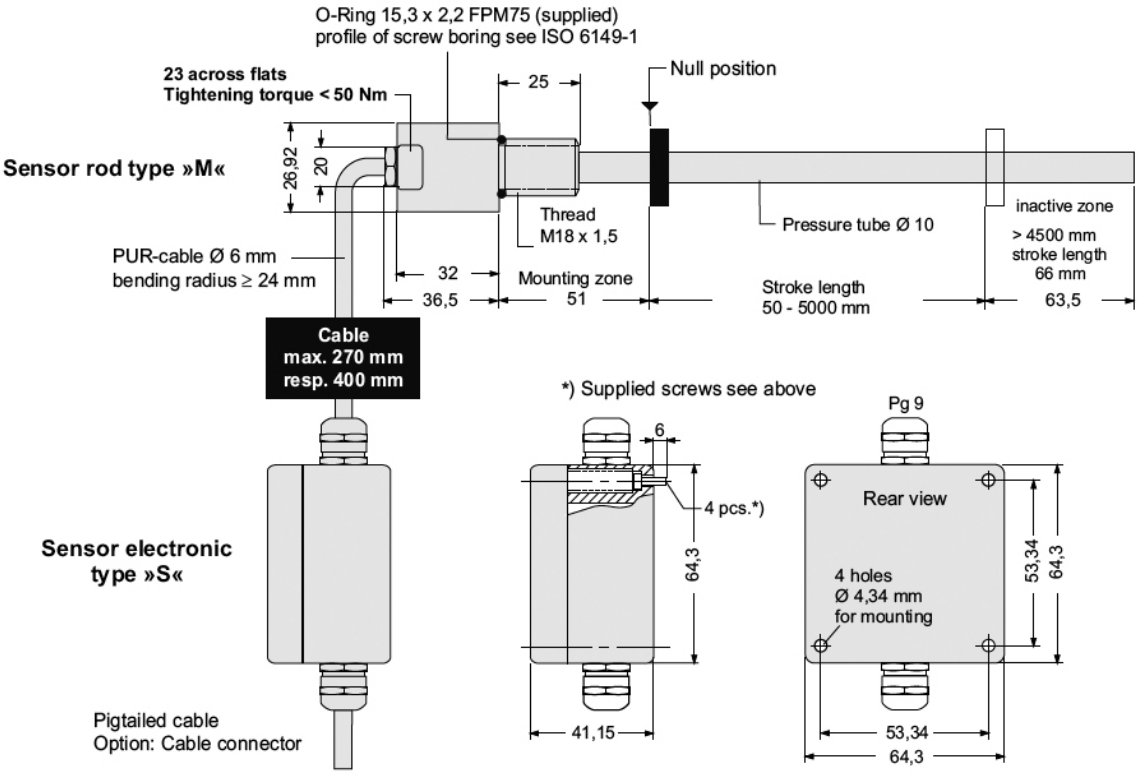
Temposonics® LD
The compact position sensor system was designed for installation in hydraulic cylinders, specifically for use in standard clevis head cylinders or any space limited cylinder applications.
• The pressure proof stainless steel sensor rod with fitting or threaded flange protects the sensing element in which gives rise to the measurement signal. It fits into the bored piston rod.
• The external standard industrial housing accomodates the modular electronic interface with active signal conditioning. The sensor electronic is connected to the basicsensor via inside terminal screws and to the controller with integrated cable outlet.
• The position magnet, the only moving part is mounted on the piston bottom. The permanent magnet travels wearfree and contactless along the stationary sensor tube. Its magnetic field starts the measurement signal through sensor's rod wall.

LD with fitting flange



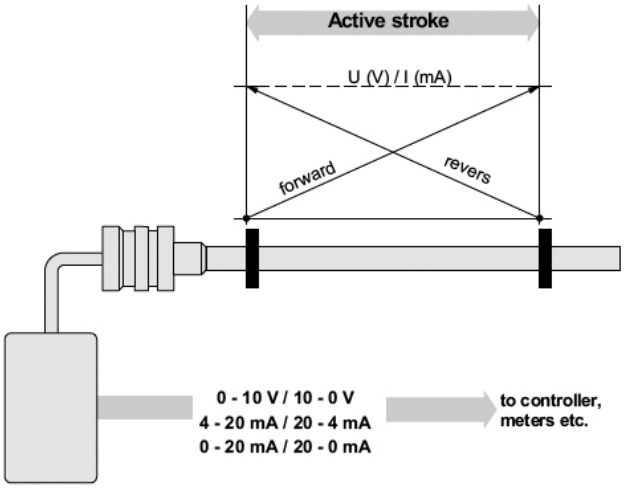
*) Supplied screws:
1) M4x12, DIN 912A2, mounting plate black anodized (from F-No. 06190054)
2) 8-32UNC-2B, mounting plate silver anodized (up to F-No. 06190053)

LD with threaded flange



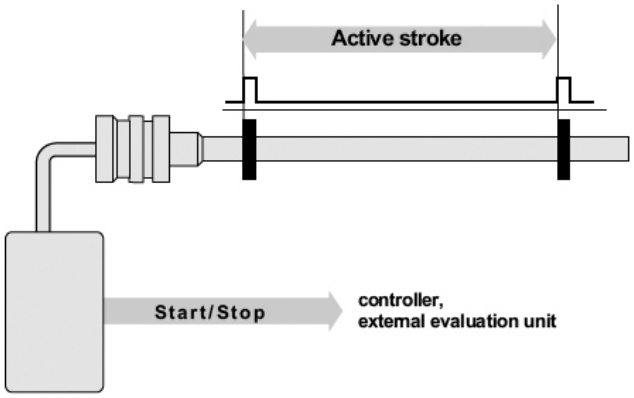
Analog Output

Temposonics® LD sensors provide direct analog outputs, including voltage (0-10 V) and current (4-20 or 0-20 mA), forward and reverse acting. Resolution is only limited by the output ripple. Since the outputs are direct, no signalconditioning electronics are needed when interfacing with controllers or meters.



Digital Start/Stop pulse

Digital LD sensor is equipped with a start/stop output. The sensor requires a start signal from an external indicator in onsite control system and returns a signal, corresponding to the magnet position. The time elapsed between the two signals is proportional to the magnet position, i.e. to the displacement. Time measurement is by the indicator and used for calculating the position value. Generation and evaluation of the start/stop pulse is made by a customized Start/Stop interface module of many controller companies.



Sensor field programming

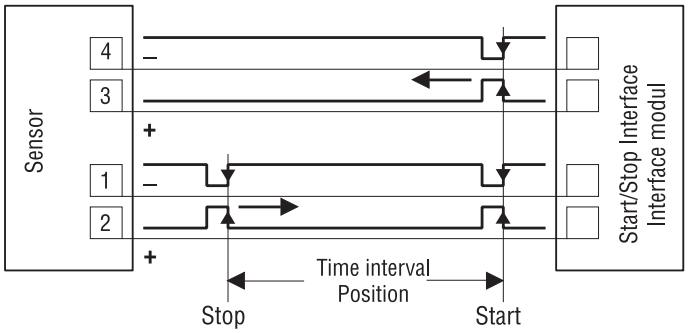
LD sensors are preconfigured at the factory by model code designation. If needed, Temposonics offers different external service tools for modifying sensor parameters inside the **active electrical stroke** (50 mm minimum clearance between setpoints) via the standard connection cable. There is no need to open the sensors electronics.
Following tools are available:

1. Handheld-Programmer G-Analog
for setups of measuring length inside the ordered output by pushing up/down-buttons.



2. PC-Programmer G-Analog
This hardware converter is required to communicate via serial port of Windows PC to the sensor. Customized settings are possible by using a Temposonics programming software (CD-ROM) for:
1. Null and Span
2. Forward and reverse acting
3. Output: Voltage/Current output values encl. range

Logic diagram Start/Stop

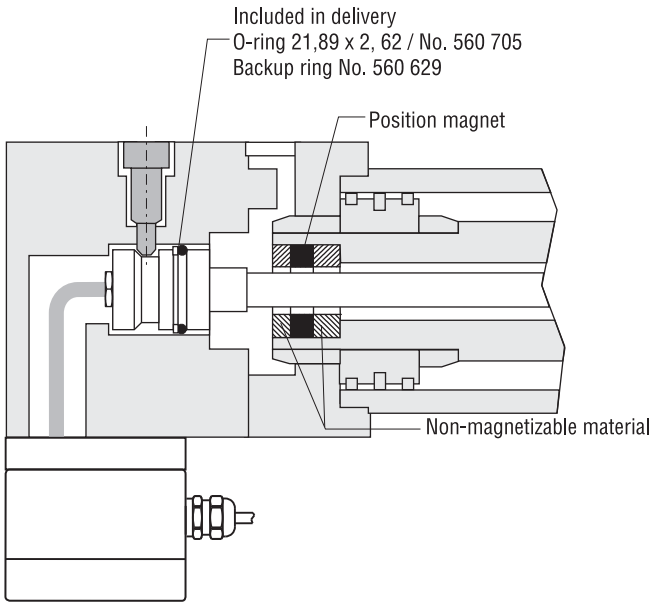


Cylinder installation
Temposonics® LD is designed for installation into hydraulic cylinders. Mounting of a LD sensor requires the use of a O-ring (black) and a backup-ring (orange). Both are supplied with the sensor. The sensor will be fixed via süecial screw.
Interconnection cable
When mounted in the manner as shown below, interconnection cable is shielded according to EMC standard at the cylinder end cap. However, when the LD sensor is mounted in an alternative way, proper care must be taken to shield the interconnection cable.

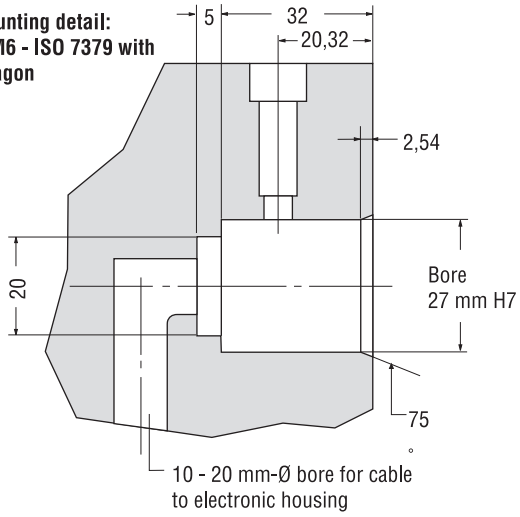
When installing the sensor in the cylinder notice following:
- Magnet must not slide along the sensor tube.
- The bore in the piston rod and type of sealing ate determined by cylinder manufacturers as that depand on hydraulic pressure and piston velocity. We recommend 13 mm bore diameter at minimum. Do not exceed peak pressure.
- Protect sensor rod from wear.

Mounting ring magnet
For accurate position measurements mount the magnet with non-magnetizable material (screws, etc.).

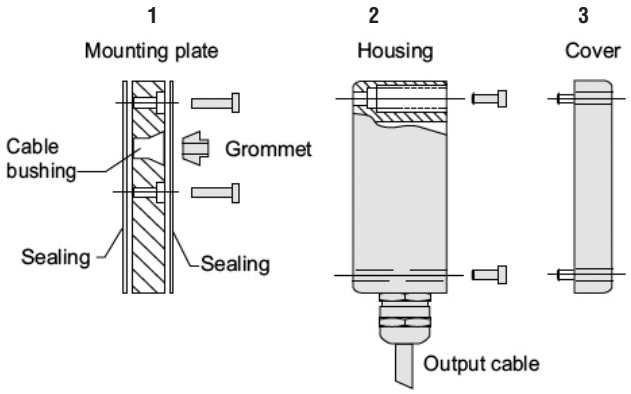
Rod style »S« with Electronics Housing style Typ »B«



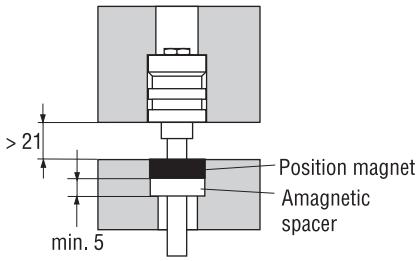
Example mounting detail:
Setscrew 8 M6 - ISO 7379 with internal hexagon



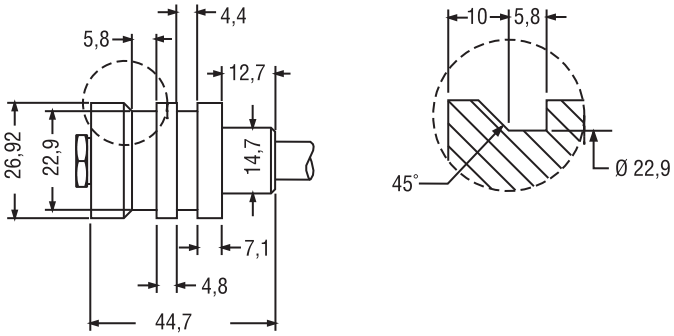
Monting Sensor electonic type »B«



Minimum tolerances for magnetizable material



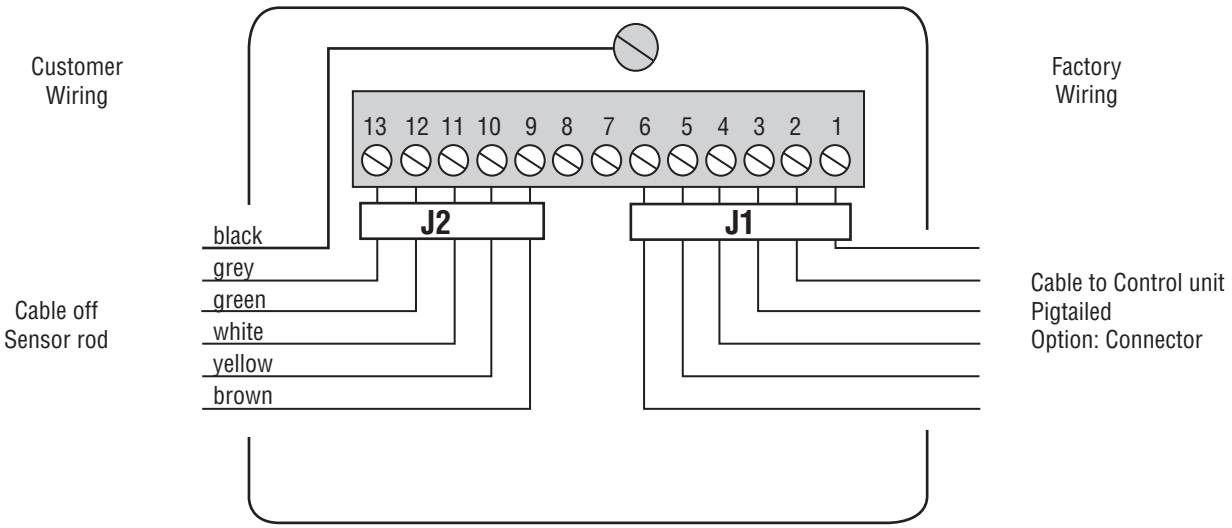
Detail: Flange



ATTENTION
Only the mounting of sensorsystem as shown here fullfill the EMC standards of Electromagnetic Emission and Immunity.

All dimensions in mm

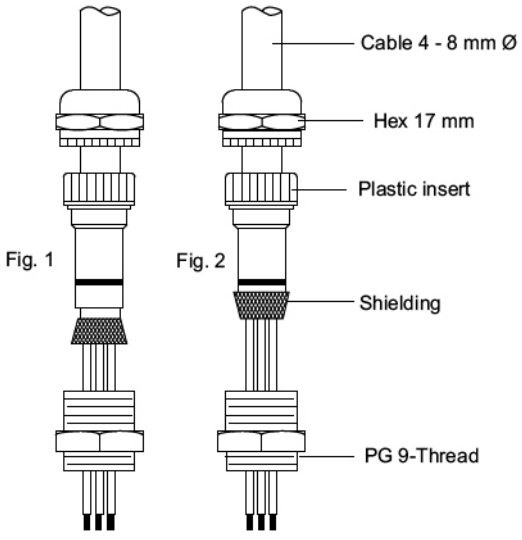
Sensor Electronics Housing



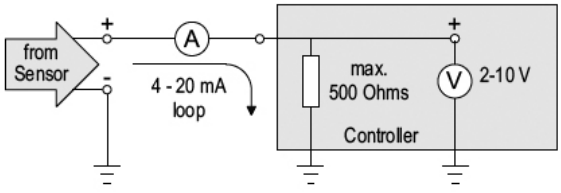
Terminal	Colour	Function
9	brown	V in
10	yellow	SE out
11	white	GND
12	green	WG (-)
13	grey	WG (+)
Screw	black	Frame GND

⚠ For side entry housing connect skield on EMC cable gland

Cable gland PG 9-EMC
EMC standard screwed cable gland for shielded cable. Simply to handle, as the cable shield must be removed backup over the plastic insert.



Typical 4 - 20 mA wiring



1. Start/Stop Output

Terminal	Colour	Function	Option: Connector
1	white	DC Ground (0 V)	Pin 6
2	pink	Stop (+)	Pin 2
3	yellow	Start (+)	Pin 3
4	grey	Stop (-)	Pin 1
5	green	Start (-)	Pin 4
6	brown	+24 VDC	Pin 5



Front view male insert

2. Analog Output

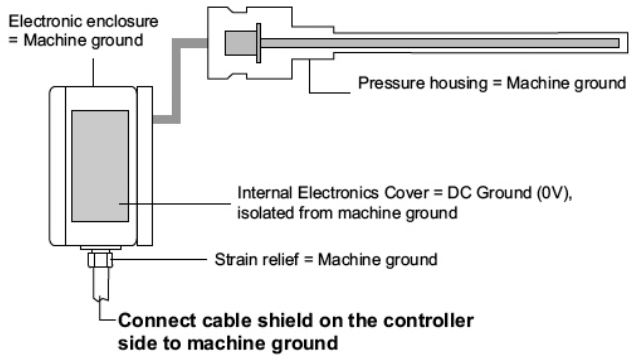
Terminal	Colour	Function	Option: Connector
1	white	DC Ground (0V)	Pin 6
2	pink	DC Ground	Pin 2
3	green	PC Programmer only	Pin 4
4	grey	0-10, 10-0 V, 4(0)-20, 20-(0)4 mA	Pin 1
5	yellow	PC Programmer only	Pin 3
6	brown	+24 VDC	Pin 5



Front view male insert

⚠ **Wiring of 10-0 V and 20-4(0) mA outputs is valid for LD sensors from fabrication # (F-No.) 0546 xxxx.**

Typical Grounding



⚠ **Cable shield and DC Ground have to be isolated separately!**

All dimensions in mm

Temposonics® LD [ ] [ ] [ ] [ ] [ ] [ ] [ ] **M** [ ] [ ] [ ] [ ] **2** [ ] [ ] [ ] [ ]

Sensor rod style
S - Fiting flange (with housing »B« only)
M - Threaded flange (with housing »S« only)

Sensor electronic housing style
B - Bottom cable entry
S - Side cable entry

Cable type electronic housing
R - PVC-cable
H - PUR-cable

Cable outlet
PT - Pigtailed
D6 - Cable with 6 pin male connector

Cable length, electronic housing
02 - 2 meters, Standard
01-10 - 01 up to 10 meters

Measuring length
0050 - 5000 mm
(up to 1000 mm in 50 mm steps; up to 5000 mm in 250 mm steps; **Option:** In 5 mm steps)

Input voltage
2 - +24 VDC

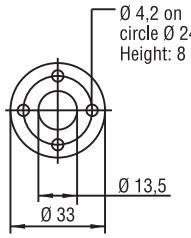
Output signal
R0 - Start/Stop
V8 - 0-10 V
V9 - 10-0 V
A4 - 4-20 mA
A5 - 20-4 mA
A6 - 0-20 mA
A7 - 20-0 mA

Integral cable length of Sensor rod
L1 - 270 mm
L2 - 400 mm

Lieferumfang:
- Messstab
- Sensorelektronik

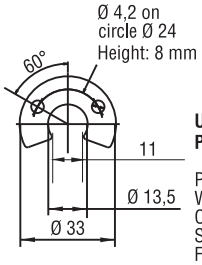
Magnete und Zubehör bitte extra bestellen.

Position magnets (order seperately)



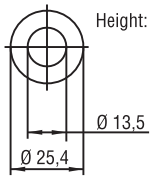
Ring magnet OD33
Part No. 201 542-2

Composite PA-Ferrite-GF20
Weigth ca. 14 g
Operating temperature:
-40 ... +100°C
Surface pressure max. 40 N/mm²
Fastening Torque for M4 screws max. 1 Nm



U-Magnet OD33
Part No. 251 416-2

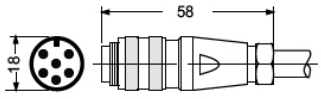
PA-Ferrit-GF20
Weigth ca. 11 g
Operating temperature: -40 ... +100°C
Surface pressure max. 40 N/mm²
Fastening torque for M4 screws max. 1 Nm



Ring magnet OD25,4
Part No. 400 533

Composite: PA-Ferrite
Weigth ca. 10 g
Operating temperature:
-40 ... +100°C
Surface pressure max. 40 N/mm²

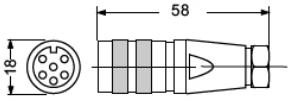
Male connector M16 wired on cable



6 pin DIN male connector
Part No. 370 372

Housing: Zinc, nickel plated
Termination: Solder
Contact insert: Silver plated
Cable clamp: PG 7
Cable-Ø: 6 mm

Mating female connector M16



6 pin DIN female connector
Part No. 370 623

Accessories	Part No.
Ring magnet OD33, Standard	201 542-2
U-Magnet OD33	251 416-2
Ring magnet OD25,4	400 533
6 pol. female cable connector M16	370 623
O-Ring 21,89 x 2,62	560 705
O-Ring 15,3 x 2,2 FPM	401 133
Backup ring	560 629

From F-No. 0546 xxxx LD-Analogue sensors are adjustable with following servicetools:

Handheld-Programmer G-Analogue	253 294
PC-Programmer G-Analogue incl. power supply (100-240 VAC/24 VDC), cable and programming software (CD)	253 145

All dimensions in mm

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